

Mathematic toolbox : Krigeage

Classical hypothese : f is a realisation of a centered gaussian covariance function k.

## Property : krigeage formula

tions of f.

Let be  $Y \sim PG(0, k)$ . Let  $Y_n = (y_1, \ldots, y_n)$  be the vector of evaluations  $X_n = (x_1, \ldots, x_n)$ . Then the law of Y(x) given the  $\sigma$ -field  $\mathcal{F}_n := \sigma(X_n, \sigma)$ follows the gaussian distribution with parameters :

$$m_n(x) = k_n(x)^T K_n^{-1} y_n$$
  
$$c_n(x, x') = k(x, x') - k_n(x)^T K_n^{-1} k_n(x')$$

with  $k_n(x) = [k(x_1, x), \dots, k(x_n, x)]'$  and  $K_n = [k(x_i, x_j)]_{1 \le i, j \le n}$ . We related to the set of  $c_n(x,x).$ 

Estimator : In this model we have considered the two following estimates the empirical quantile) :  $\mathbf{\hat{q}}^{(\mathbf{n})} = \mathbf{\hat{q}}^*_{\mathbf{n}}(\mathbf{m}_{\mathbf{n}})$  and  $\mathbf{\tilde{q}}^{(\mathbf{n})} = \mathbb{E}_{\mathbf{n}}[\mathbf{\hat{q}}^*_{\mathbf{n}}(\mathbf{Y})].$ 

Warning : Naive implementation leads us to inverse a big matrix ==

Active learning : We want strategies in which we choose points to eval

Property : 1-step update formula (see [3])

 $m_{n+1}(x) = m_n(x) + \frac{c_n(x_{n+1},x)}{s_n^2(x_{n+1})} (Y(x_{n+1}) - m_n(x_{n+1}))$   $s_{n+1}^2(x) = s_n^2(x) - \frac{c_n^2(x_{n+1},x)}{s_n^2(x_{n+1})}$   $c_{n+1}(x,y) = c_n(x,y) - \frac{c_n(x_{n+1},x)c_n(x_{n+1},y)}{s_n^2(x_{n+1})}$ 

## UNCERTAINTY PROPAGATION AND ESTIMATION OF A QUANTILE

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