

Conditional quantile sequential estimation for stochastic codes

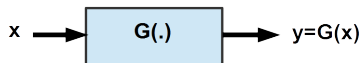
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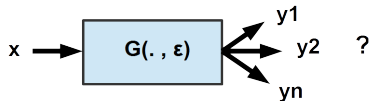
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What is a stochastic code ?

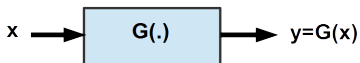


Numerical code : $Y=G(X)$
 $G(x)$ is a real number

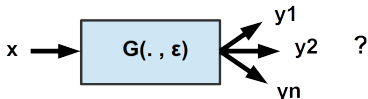


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What is a stochastic code ?



Numerical code : $Y=G(X)$
 $G(x)$ is a real number



Stochastic code : $Y=G(X, \epsilon)$
 $G(x, \epsilon)$ is a random variable

Goal : Estimate the **quantile** of the law $\mathcal{L}(G(X, \epsilon)|X = x)$ using as few as possible calls to the code.

- Stochastic algorithm for the **quantile of level α for the law X** :

$$\begin{cases} \theta_0 & \in \mathbb{R} \\ \theta_{n+1} & = \theta_n - \frac{1}{n^\gamma} (\mathbf{1}_{X_{n+1} \leq \theta_n} - \alpha) \end{cases}$$

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- Idea :
 - 1) Fix a budget N .
 - 2) Take an inputs sample (X_1, \dots, X_N) .
 - 3) Observe the corresponding outputs (Y_1, \dots, Y_N) .
 - 4) **Develop an algorithm we can apply for each x and using only the previous information.**

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- New algorithm using **stochastic algorithm** and **k-nearest neighborhoods** theory :

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- What are the **optimal parameters** γ and β ? Under which assumptions is the algorithm **convergent**? What about **non-asymptotic** results?

Let us introduce the map

$$\mathcal{C}: \begin{cases} (E, d_H) \longrightarrow (\mathcal{M}^1(\mu), d_{VT}) \\ A \longmapsto \mathcal{L}(Y|X \in A) \end{cases}$$

- (E, d_H) : set of the sets on the metric space $(\mathbb{R}^d, \|\cdot\|)$ with d_H the Hausdorff distance.
- $(\mathcal{M}^1(\mu), d_{VT})$: set of the probability measures with d_{VT} is the total variation distance.

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Assumption A1 The function \mathcal{C} is M - Lipschitz.

Assumption A2 The law of inputs has a density function and this density is lower-bounded by a constant $C_{inputs} > 0$ on its support.

$$\Rightarrow \forall \theta_1 \in \text{Supp}(X), (F(\theta_1) - F(\theta^*)) (\theta_1 - \theta^*) \geq C_{inputs} (\theta_1 - \theta^*)^2.$$

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$\Rightarrow \forall x, \theta_n(x)$ is bounded a.s uniformly in ω . Let us denote R the such uniform bound of $(\theta_n - \theta^*)^2$.

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Assumption A4 For each x , the law $g(X, \epsilon) | X = x$ has a density which is lower-bounded by a constant $D_{code}(x) > 0$.

$$\Rightarrow \text{avoids technical developments to deal with } \mathbb{E}(\|X - x\|_{(k_n, n)}) \text{ of } \mathbb{P}(X \in kPPV_n(x)).$$

Theorem : almost sure convergence

Let x be a fixed input. Under assumptions **A1** and **A2**, the algorithm at x is a.s convergent if and only if $\frac{1}{2} < \gamma < \beta < 1$.

Theorem : rate of convergence

Let x be an fixed input. Under hypothesis **A1**, **A2**, **A3** and **A4**, for all $0 < \gamma < 1$, $0 < \beta < 1$ and $1 > \epsilon > 1 - \beta$, for $n \geq 2^{\frac{1}{\epsilon - (1 - \beta)}} := N_0$,

$$\mathbb{E} \left[(\theta_n(x) - \theta^*(x))^2 \right] \leq R \exp \left(-\frac{3n^{1-\epsilon}}{8} \right) + a_0(x) \exp \left(-2D_{\text{code}}(x) \sum_{k=1}^n \frac{1}{k^{\gamma+\epsilon}} \right) + \sum_{k=1}^n \exp \left(-2D_{\text{code}}(x) \sum_{i=k}^n \frac{1}{i^{\gamma+\epsilon}} \right) \beta_k$$

where

$$\beta_n = R \exp \left(-\frac{3n^{1-\epsilon}}{8} \right) + 2\sqrt{RMD}(d) \gamma_{n+1} \left(\frac{k_n}{n+1} \right)^{\frac{1}{d}+1} + \gamma_{n+1}^2 \frac{k_n}{n+1},$$
$$D(d) = \sqrt[d]{2} \left(1 + \frac{8}{3d} + \frac{1}{\sqrt[d]{C_{\text{input}} H(d)}} \right) \text{ and } H(d) = \frac{\pi^{\frac{5}{2}}}{\Gamma(\frac{d}{2}+1)}.$$

Theorem : best parameters

Under the same hypothesis, the mean square error decreases more rapidly when parameters are $\gamma = \frac{1}{1+d}$ and $\beta = \gamma + \eta$ where $\eta > 0$ is as small as possible. We indeed obtain with these parameters for $n \geq \max(N_0, N_1)$

$$\mathbb{E} \left[(\theta_n(x) - \theta^*(x))^2 \right] \leq \frac{C_1}{n^{\frac{1}{1+d} - \eta'}}$$

where constants are explicitly known.

Dimension 1

We tested two models for $X \sim \mathcal{U}([-1, 1])$, $\epsilon \sim \mathcal{U}([-0.5, 0.5])$ and $x = 0$: $g(X, \epsilon) = X^2 + \epsilon$ and $g(X, \epsilon) = |X| + \epsilon$:

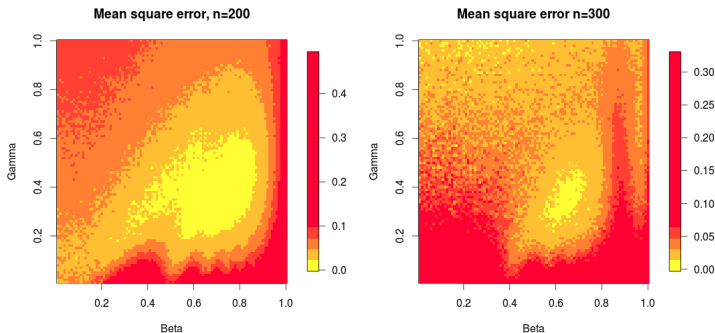


FIGURE: Convergence of the mean square error in function of β and γ .

Dimension 2 and 3

We tested the model $g(X, \epsilon) = \|X\|^2 + \epsilon$ for $X \sim \mathcal{U}([-1, 1]^d)$, $\epsilon \sim \mathcal{U}([-0.5, 0.5])$ and $x = 0_{\mathbb{R}^d}$.

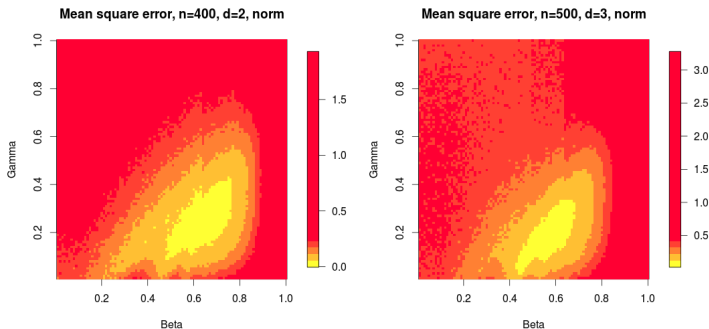


FIGURE: Convergence of the mean square error in function of β and γ .

Conclusion :

- We have introduced an algorithm to estimate the conditional quantile of the output of a stochastic code.
- We know how to tune the parameters to obtain the best rate of convergence.
- Numerical simulations show that results are good in practice.

Perspectives :

- Adapt the proof for less restrictive assumptions.
- Improve the rank N_0 .
- Apply this algorithm on real data (EDF and renewable energies).

Thank you for your attention